



Course & Kit Content  
Of  
**MATLAB with Robotics**

**Duration 7 Days**

**Kit Partner**

**ROBOMART.com**

**Corporate Office**

Robosapiens Technologies Pvt. Ltd.  
B 5, Block 'C', Sector-31,  
Noida-201301

Email: [info@robosapi.com](mailto:info@robosapi.com)/  
Website: <http://www.robosapi.com>

Course Name : **MATLAB with ROBOTICS**  
Certification : By Robosapiens Technologies Pvt. Ltd.  
Fee : ` 5900/- Only  
Toolkit : **FREE** to Each Participant  
LIVE Projects Covered : **MORE THAN 20 Projects** Covered in 7 Days

## **Detailed Course Content:**

### **1. Introduction to Basic MATLAB Concepts**

- 1.1. Saving and loading a MAT-file
- 1.2. MATLAB's Command Prompt
- 1.3. Basic Reading and Writing Data from a File

### **2. Introduction to Data Storage and Manipulation**

- 2.1. Data Types and Operations on Point Values
- 2.2. Boolean and Rational
- 2.3. Strings
- 2.4. Portable Functions
- 2.5. Complex Numbers

### **3. Arrays and Matrices**

- 3.1. What is an array?
- 3.2. Introduction to array operations
- 3.3. Vectors and basic vector operations
- 3.4. Structure Arrays
- 3.5. Cell Arrays
- 3.6. Sparse Matrices

### **4. Introduction to Mathematical Manipulations**

- 4.1. Linear Algebra
- 4.2. Simple matrix manipulation
- 4.3. More complicated matrix operations
- 4.4. Differential Equation

- 4.5. Ordinary Differential Equations
- 4.6. Partial Differential Equations

## **5. Image Acquisition Tool**

- 5.1. Device Connection
- 5.2. Image Preview & Device Configuration
- 5.3. Image Data Acquisition

## **6. Image Processing Tool**

- 6.1. Display & Exploration
- 6.2. Geometric Transformation, Spatial Referencing and Image Registration
- 6.3. Image Enhancement
- 6.4. Image Analysis
- 6.5. Image Import, Export & Conversion

## **7. Introduction to Robotics**

- 7.1. History of Robotics
- 7.2. Why Robotics
- 7.3. How Robotics works
- 7.4. Application of Robotics
- 7.5. Current Industrial Robotics
- 7.6. Future of Robotics

## **8. Introduction to Sensors**

- 8.1. What is Sensor?
- 8.2. Various Basic Industrial Sensors-IR- Analog Sensor
- 8.3. IR Digital Sensor
- 8.4. Selection of Sensor
- 8.5. Basic working Technique of Sensor
- 8.6. Application of Sensor
- 8.7. How to Interface Sensor
- 8.8. How to Design Analog/Digital Sensors

## **9. Introduction to Computational Devices**

- 9.1. What is Computational Device?
- 9.2. Microprocessor
- 9.3. Microcontroller
- 9.4. Difference B/W Various Computational Devices
- 9.5. Application of various Computational Devices
- 9.6. Selection of Computational Device
- 9.7. How to use Various Computation Device
- 9.8. Work on AVR Family with Mega Series (ATmega8)

## **10. How to work on Educational & Engineering Level Actuator**

- 10.1. DC Motor
- 10.2. DC Geared Motor

## **11. Introduction to Driving System/Locomotion**

- 11.1. What is Driving System?
- 11.2. Various Types of Driving System
- 11.3. Why need Driving System

## **12. Introduction to Programming Languages**

- 12.1. Various programming Languages
- 12.2. Selection of programming Language
- 12.3. Need of Flow Diagram
- 12.4. How to write First “LED BLINKING” Code in Embedded C
- 12.5. Why always First “LED BLINKING” Code?
- 12.6. Practice on various LED Pattern
- 12.7. Debugging of Error Program

## **13. Interfacing of Anatomy of Robot**

13.1. Assembling of Robot

## **14. Introduction to USART**

14.1. Mode of Communication

14.2. Types of Communication Protocol

14.3. Difference between Different Communication Protocol (I2C, SPI, UART )











14.4. USART Registers

14.5. Programming USART

## **LIVE Projects Covered:**

1. LED Blinking
2. Sand Glass Filling of LEDs
3. Decoration LEDs/ LED Patterns Etc.
4. Sensor Interfacing
5. DC Motor Driving
6. Black Line Follower using two IR-Sensor
7. White Line Follower using two IR-Sensor
8. Wall follower Robot
9. Edge Avoider Robot
10. Intelligent Line Follower Robot
11. PC to  $\mu$ C Communication
12.  $\mu$ C to PC Communication
13. Computer Keyboard Controlled Robot
14. GUI Switch Controlled Robot
15. Image Comparison
16. Image Pairing
17. Filtering of Noise
18. Ball Tracker Robot

## **7 Days KIT Contains:**

S. No.	Name of the Component	Quantity	Figure
1	Robosapien's Atmega8 Development Board	1	
2	USB Cable A to B Type	1	
3	Robosapien's Educational and Software Material CD	1	
4	IR Digital Sensor	2	
5	150 RPM Single Shaft BO Rectangle	2	
6	Robosapiens Caster Wheel	1	
7	Robosapiens 76mm Wheel	2	
8	Robosapiens Chassis Board	1	
9	Screw Driver	1	
10	Nut Bolt Packet	1	
11	Robomart USB to TTL Bridge	1	
12	1 PIN Female to Female Jumper Wire	4	
20	Paper Beg/Box	1	